

The Millimetron antenna

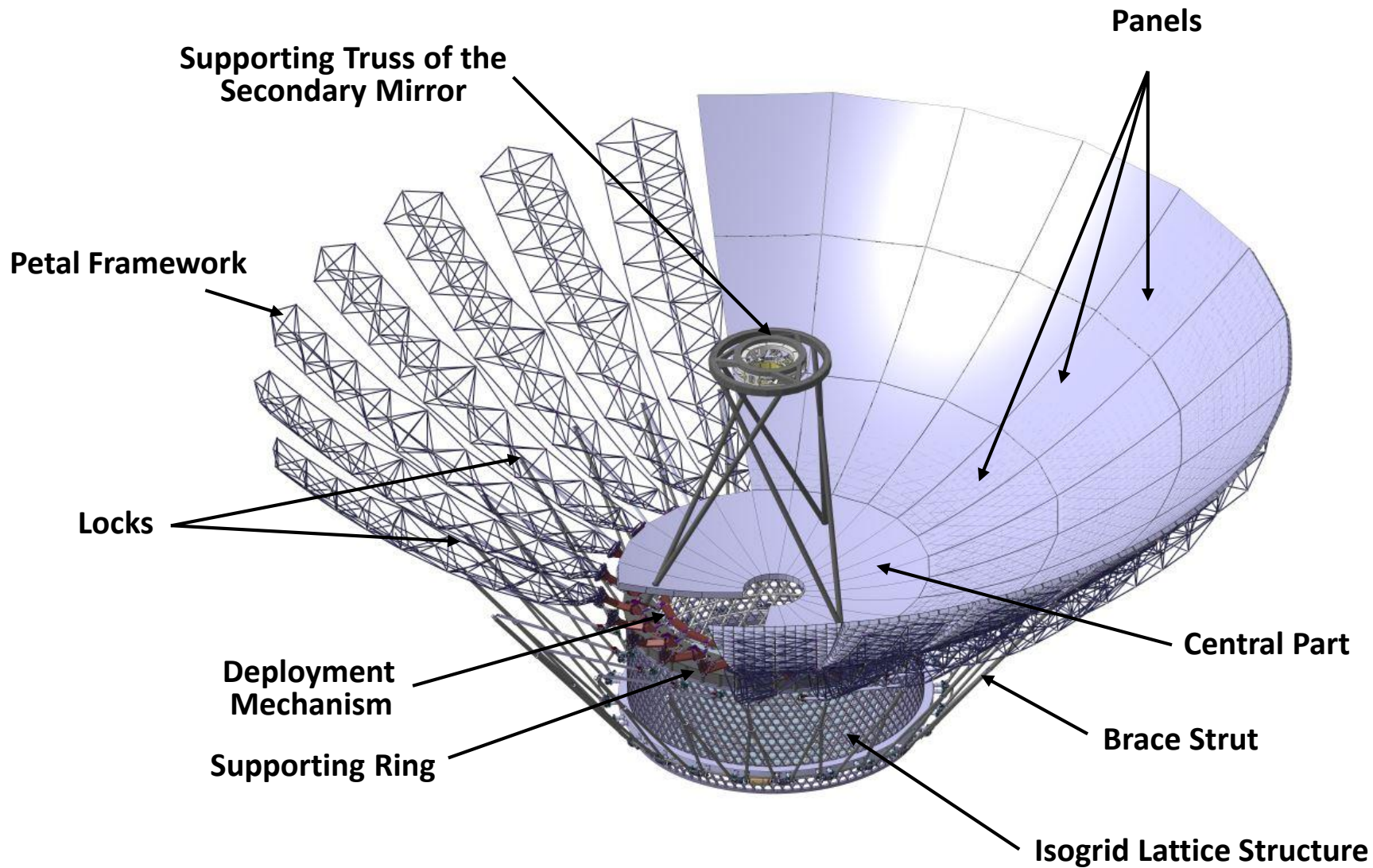


ASC LPI



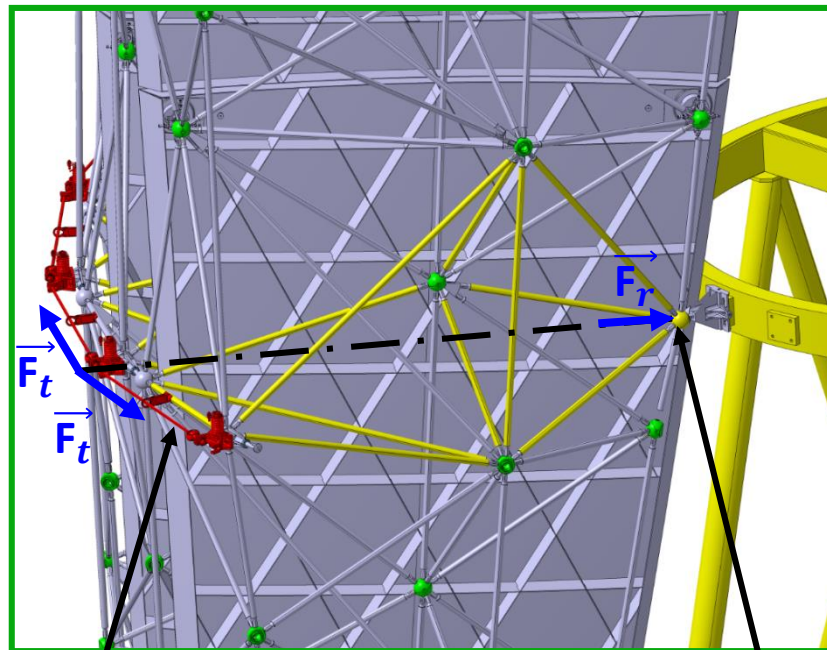
E. Golubev on behalf of the Millimetron team

Design of the Millimetron Antenna



Stowed Configuration of the Primary Mirror

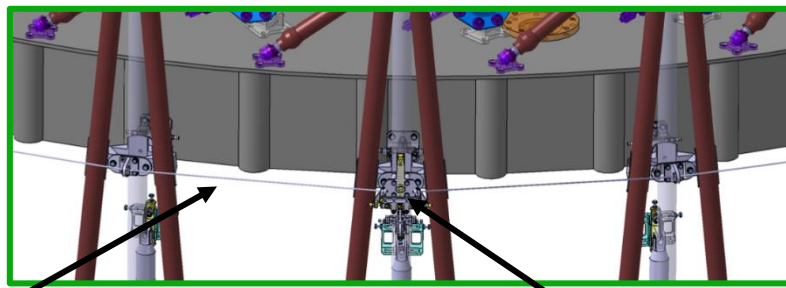
Petal fixation



External lock ring with pretensioned segmented truss

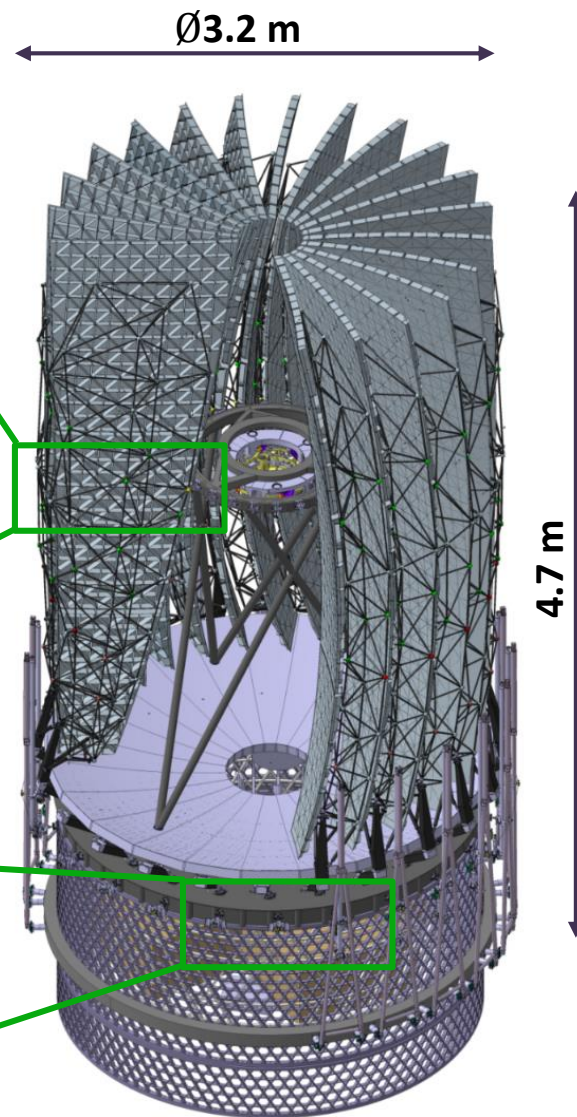
Internal lock ring
"conical socket – spherical tips"

Brace struts fixation

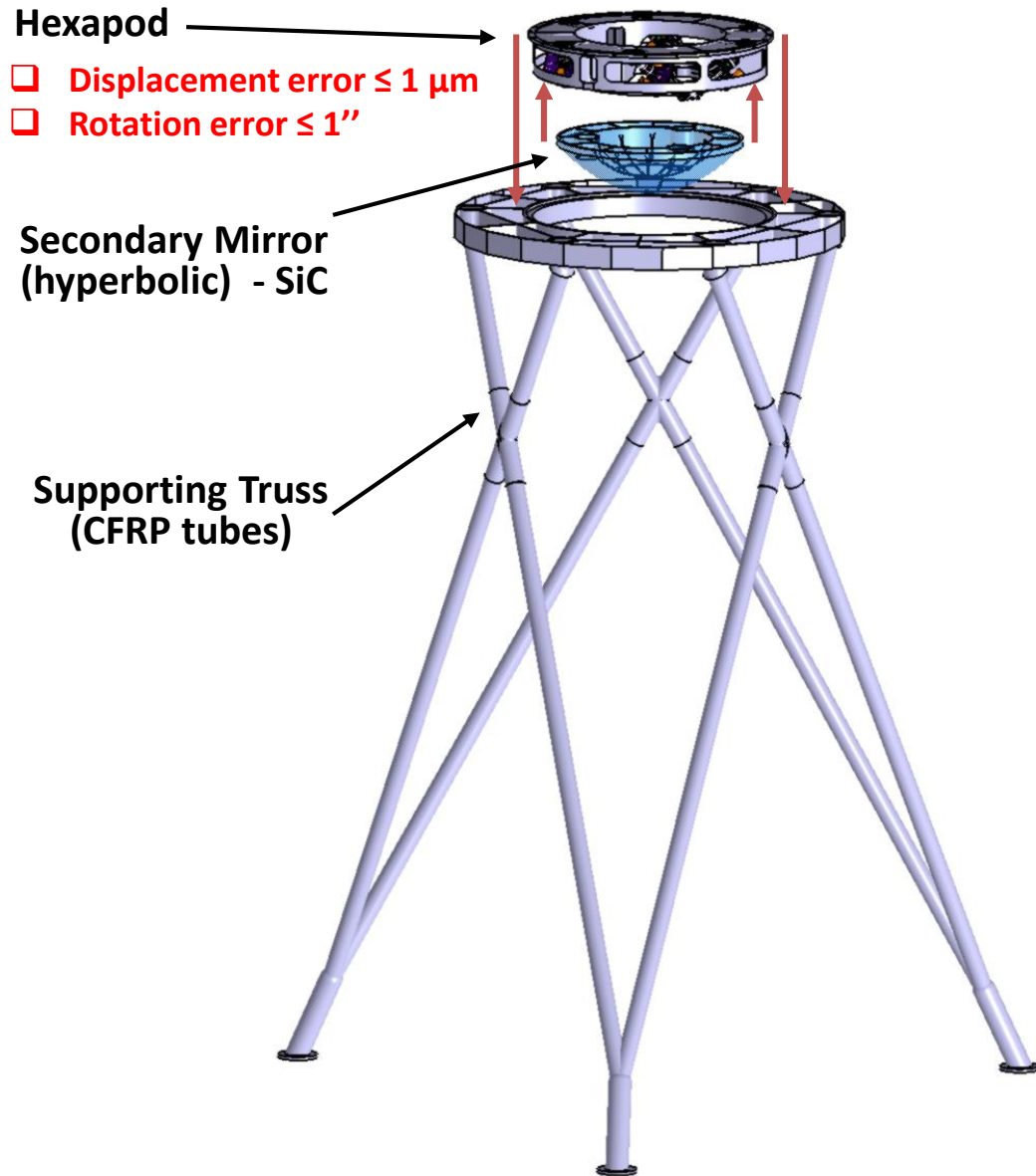


Pretensioned truss

Brace strut lock



The Secondary Mirror



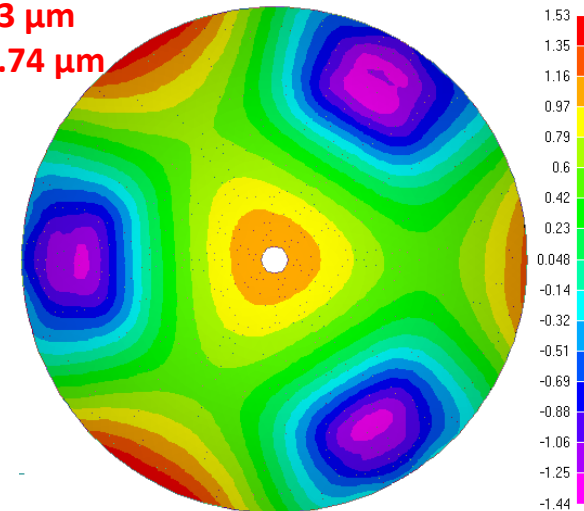
✓ Surf. Errors $\leq 1 \mu\text{m}$ (measured)
limited by CMM measurement



Scale model (1:3)

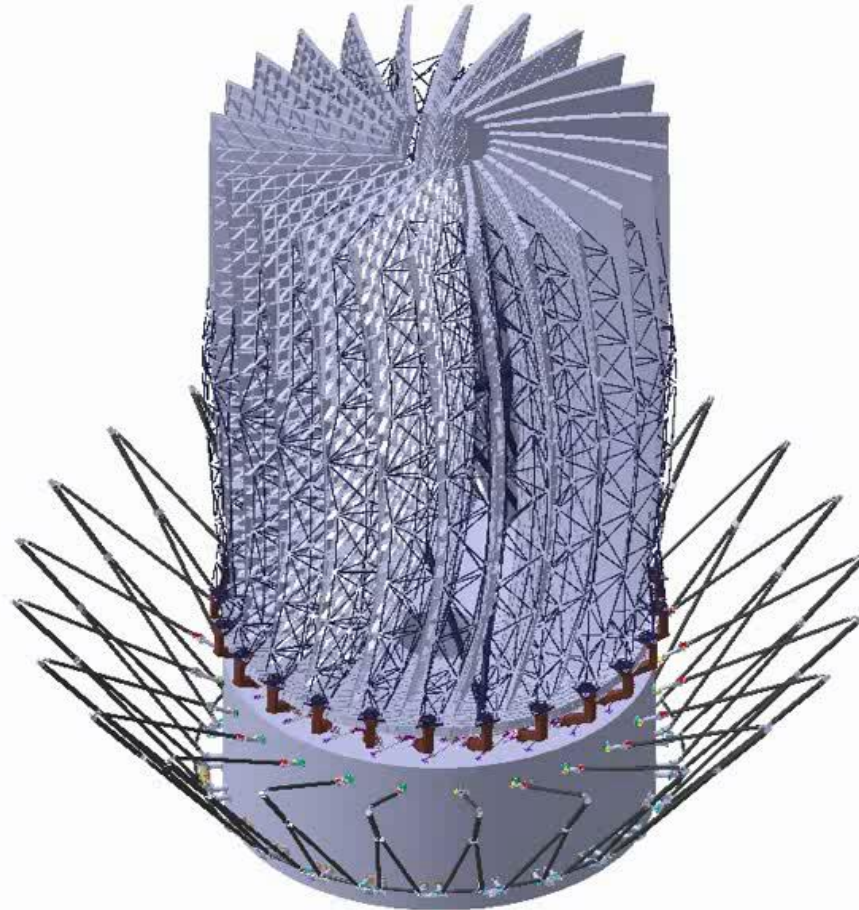
Normal distortion of the SM made from SiC
due to cool-down to 4K (calculated)

PV = $1.53 \mu\text{m}$
RMS = $0.74 \mu\text{m}$

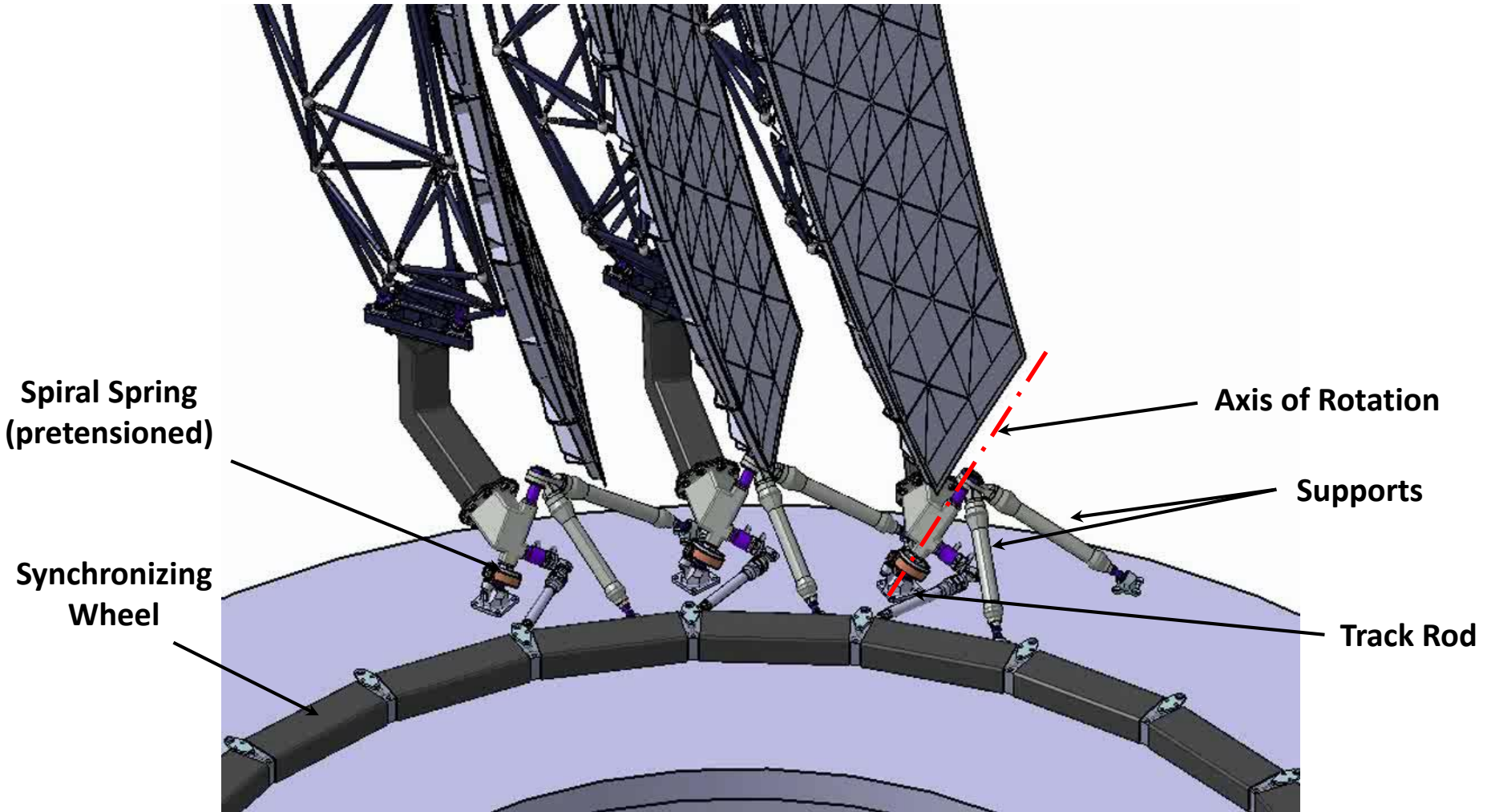


Deployment Strategy

❑ required deployment accuracy ≤ 1 mm (PV)

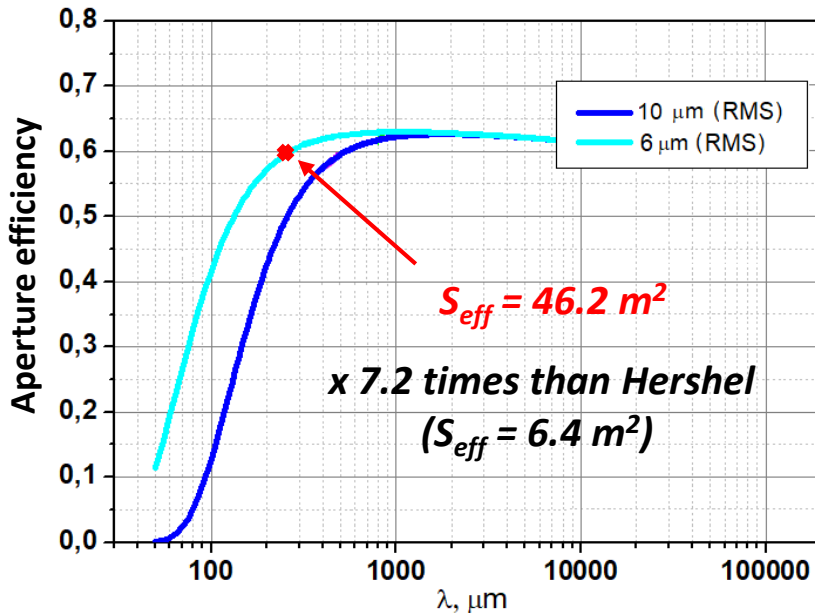
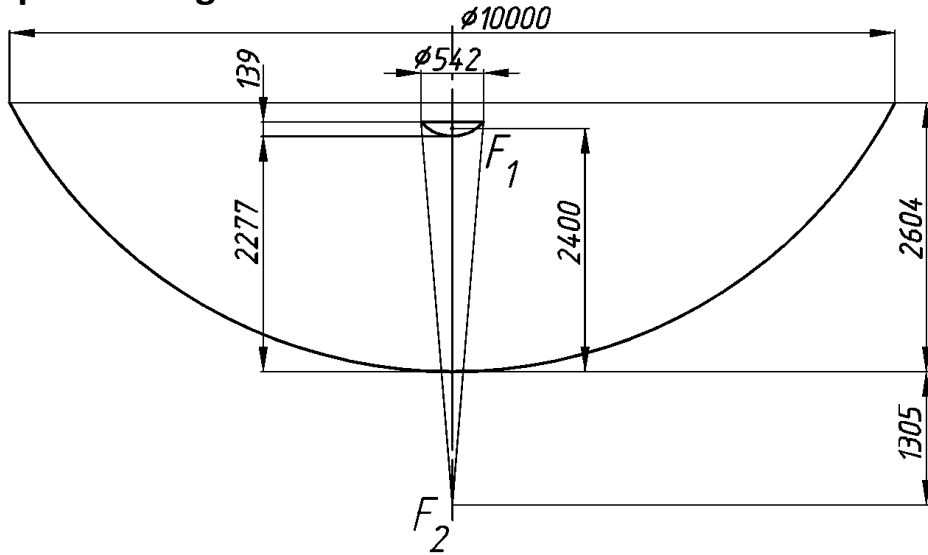


Deployment Mechanism



Millimetron antenna / Error budget

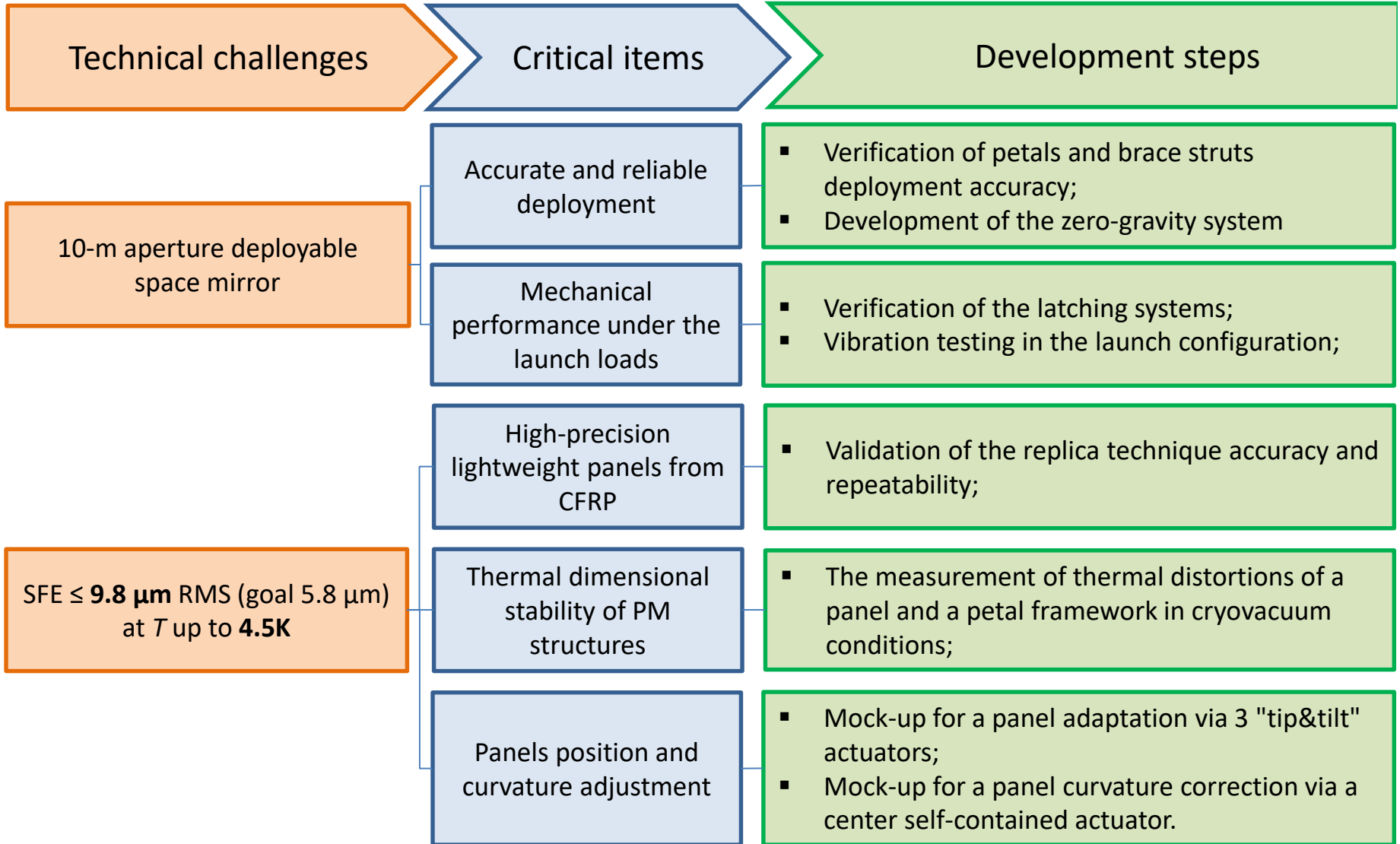
Optical design



Telescope		6 μm (RMS)
1	Primary mirror	5,8
1.1	Panels	3,6
1.2	Assembly*	0,3
1.3	Deployment*	0,7
1.4	Thermal and moisture distortions of framework*	2,8
1.5	1g offload*	0,8
1.6	Panel distortions due to adaptation	0,2
1.7	Panel curvature correction**	2,2
1.8	Adaptation	0,5
1.9	Alignment	1,0
1.10	Non-static image quality	0,2
	Total	5,3
	Margin	0,5
2	Secondary mirror	
2.1	Manufacturing	1,0
2.2	Thermal distortions	0,8
2.3	Alignment	1,0
2.4	Non-static image quality	0,2
	Total	1,6



Risks mitigation in the Primary Mirror development



Primary Mirror mock-up at November 11, 2016



Development and testing of full-scale Primary Mirror mock-up

4



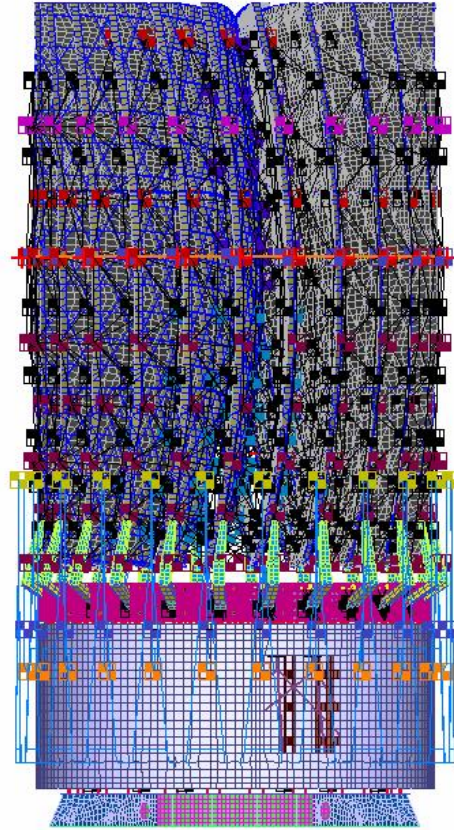
Phases of the test program:

1. Verification of deployment system performances in terms deployment accuracy and repeatability;
2. Development and verification of a zero-gravity system;
3. Verification of the latching system of petals in operational and folded positions;
4. Verification of deployment system of brace struts;
5. Vibration testing in the stowed configuration.

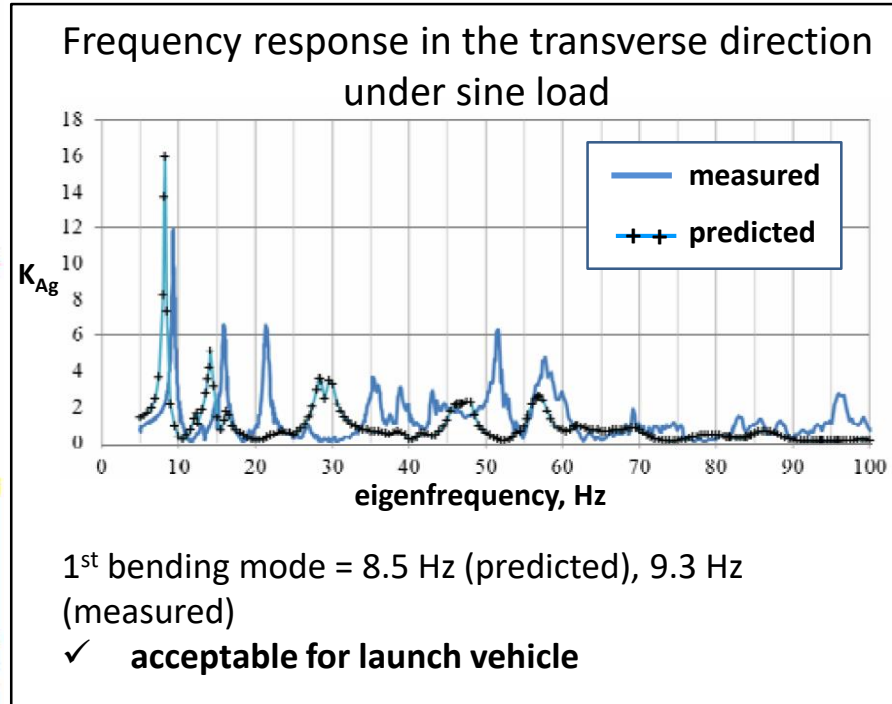
Vibration testing in the stowed configuration



Foto PM mock-up on a shaker

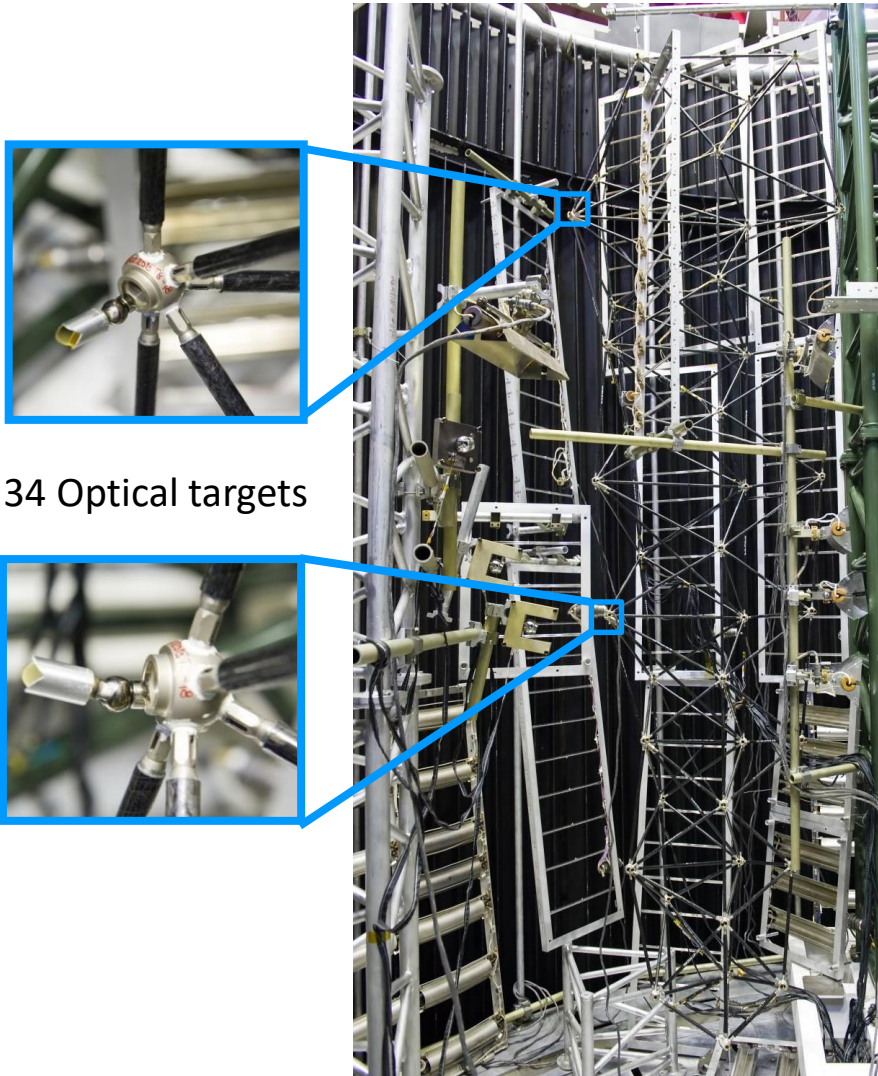


FEM of mock-up



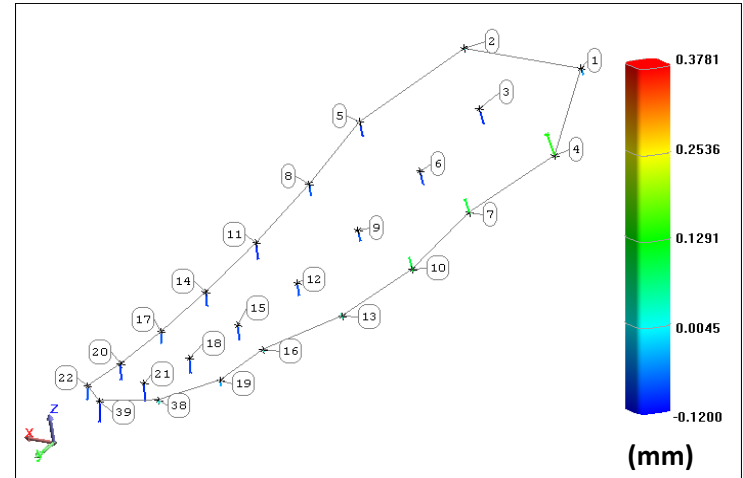
- ✓ No structural degradation and visible damage after test;
- ✓ No unexplained frequency shifts more than 5% between pre and post test;
- ✓ Latching system of PM for the stowed configuration verified.

Thermal distortions measurement of petal framework

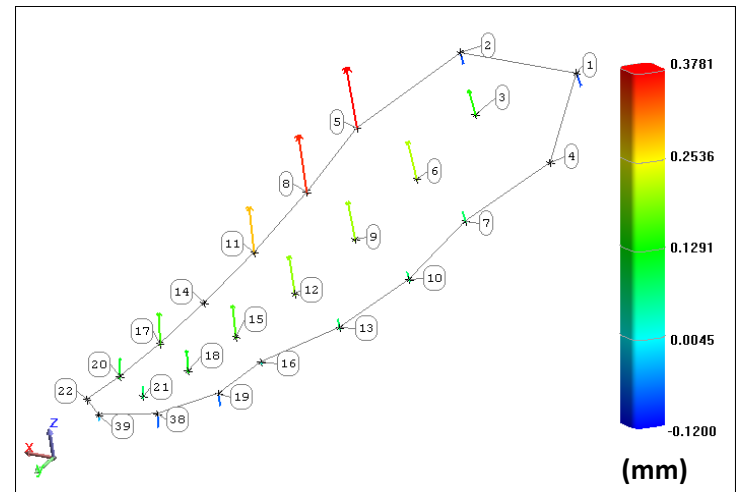


34 Optical targets

Petal framework in a thermal vacuum chamber
(Max thermal gradient $<10^{\circ}\text{C}$)



Measured distortions at $t = -140^{\circ}\text{C}$

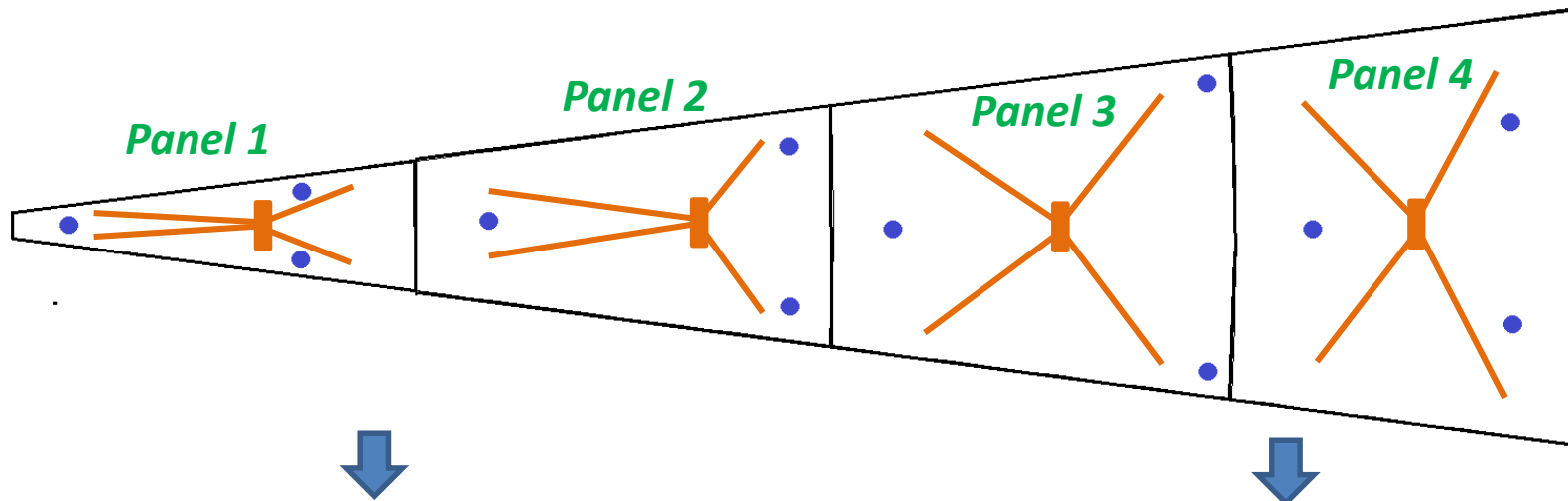


Measured distortions at $t = +140^{\circ}\text{C}$

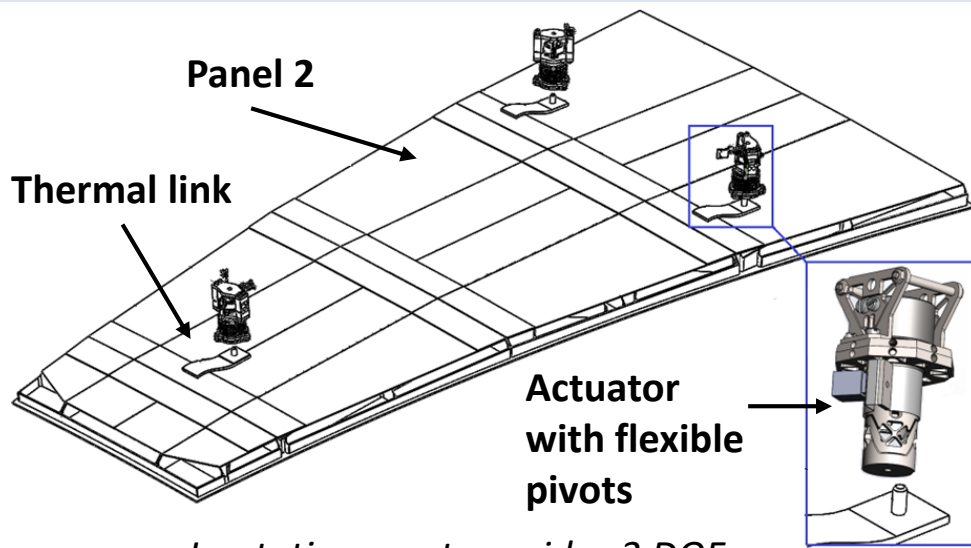
✓ Max measured distortions ≤ 0.4 mm (PV)



Panels position and curvature adjustment

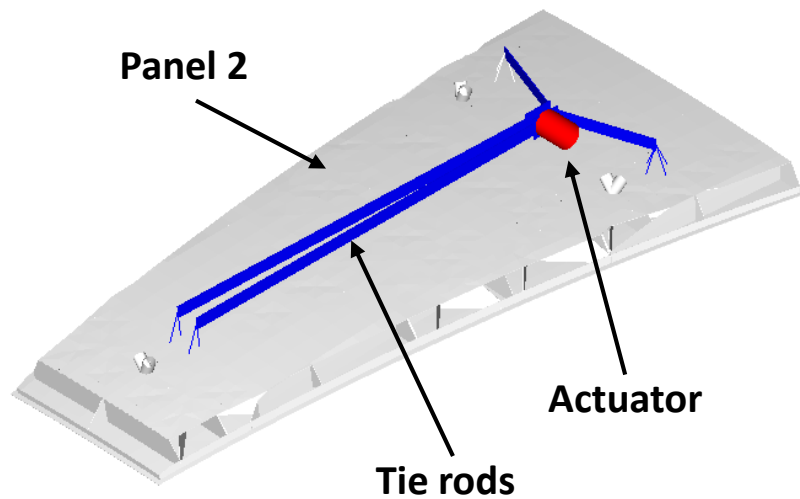


Concept of panel adaptation via 3 actuators

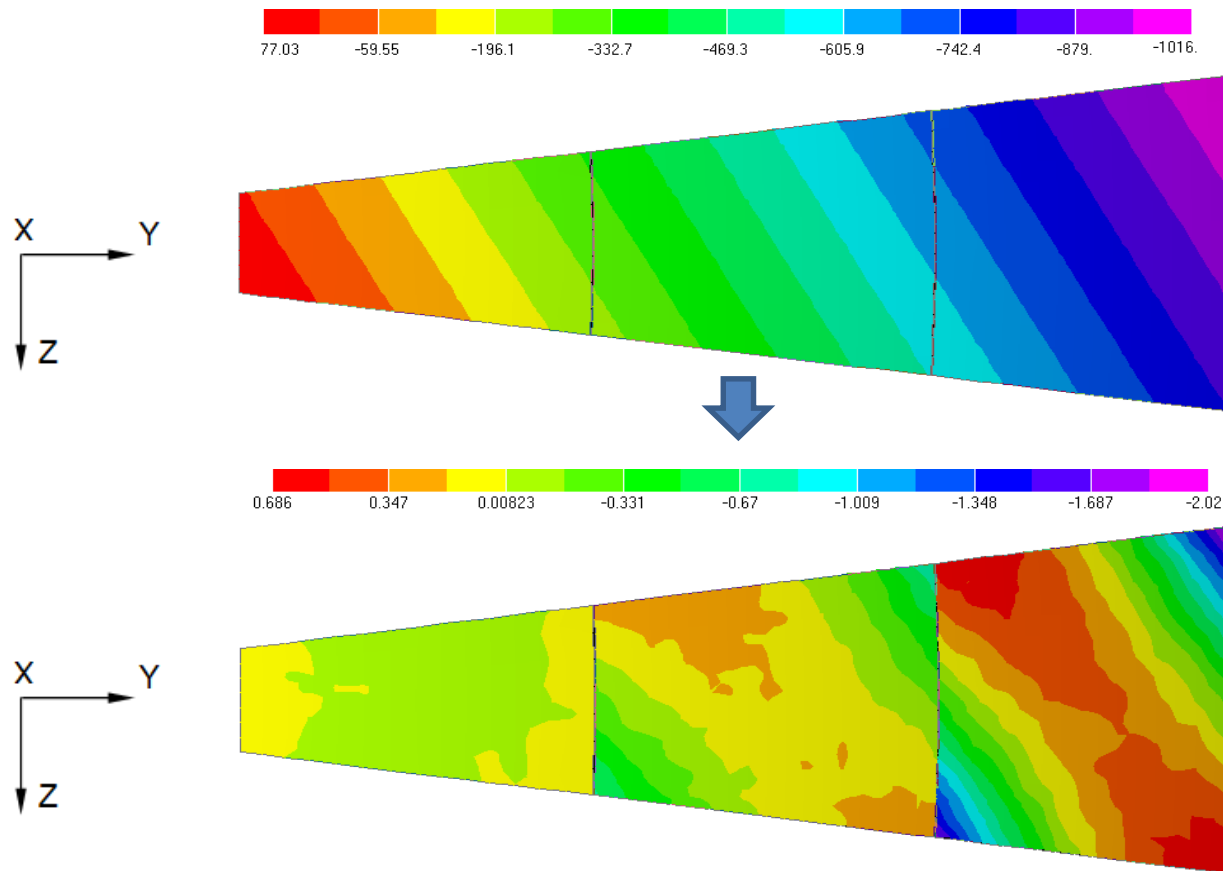


*Isostatic mount provides 3 DOF:
2 rotation and 1 displacement*

Concept of panel curvature correction



Deployment error alignment



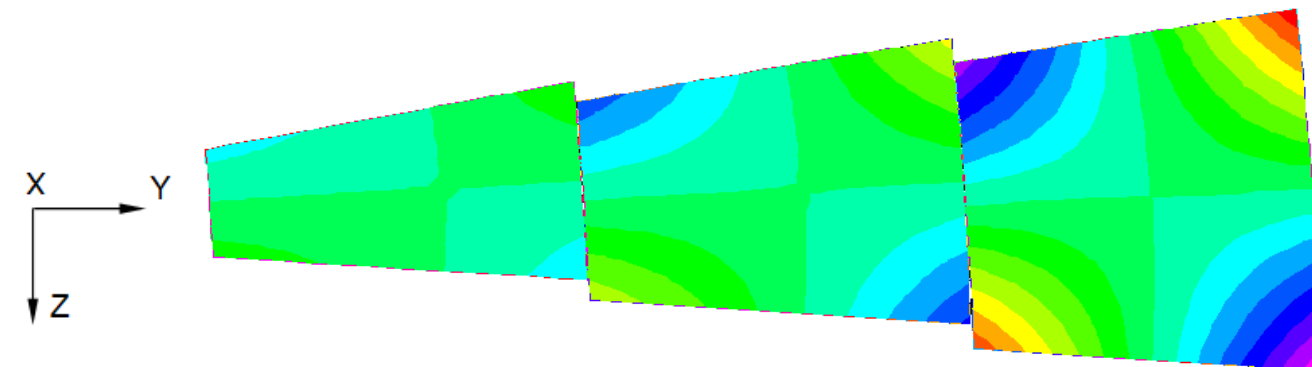
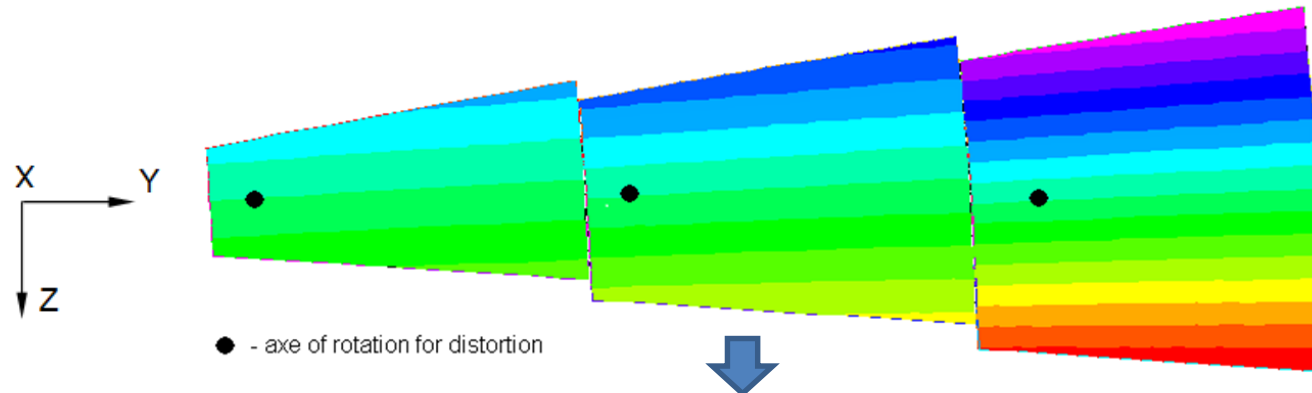
$$A_{\epsilon} = \pm 1 \text{ mm}^*$$

**Errors are caused by deviation in the turning angle of a petal around deployment axis*

Residual misalignments

	Panel 2	Panel 3	Panel 4
RMS before adjustment, μm	183	544	923
RMS after adjustment, μm	0.2	0.6	0.9
Actuator movements, μm	34/ 342/ 246	789/ 356/ 634	785/ 979/ 1094

Assembly error alignment



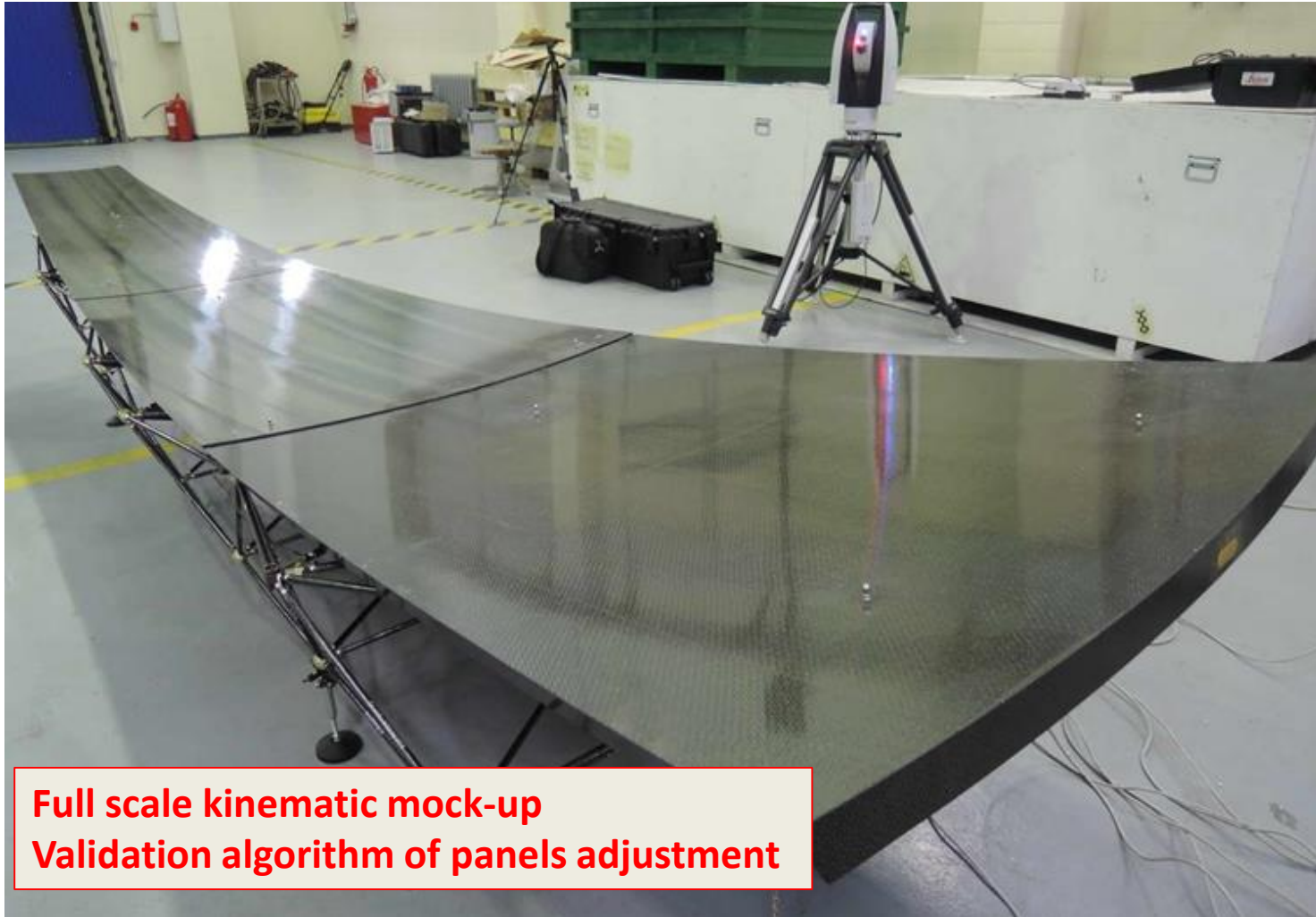
The worst case of assembly error:

Rotation over vertical axis of actuator 1 with $A_\epsilon = \pm 100 \mu\text{m}$

Residual misalignments

	Panel 2	Panel 3	Panel 4
RMS before adjustment, μm	5.6	10.6	20.4
RMS after adjustment, μm	0.2	0.4	0.7
Actuator movements, μm	4/ 34/ 25	79/ 36/ 64	78/ 98/ 109

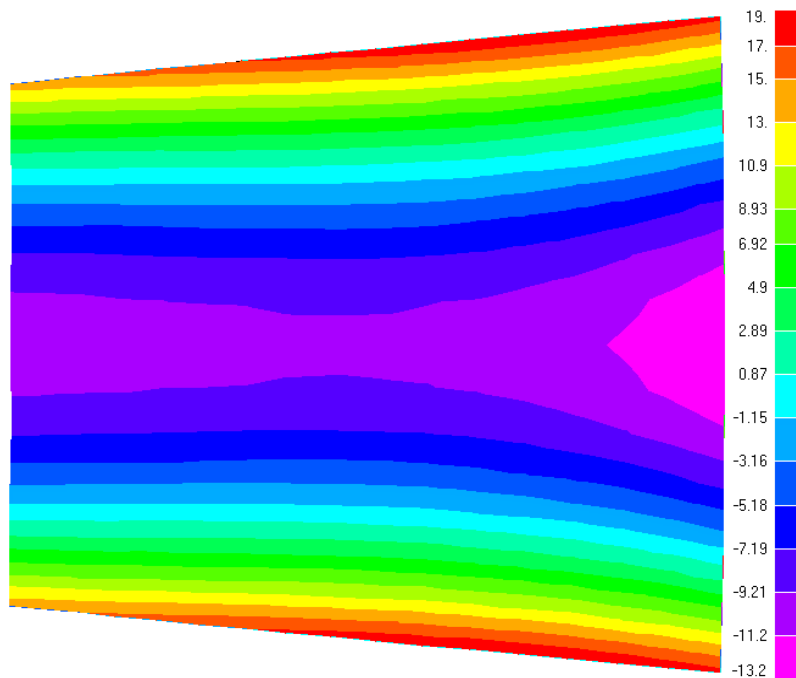
Mock-up of panel adaptation system



Full scale kinematic mock-up
Validation algorithm of panels adjustment

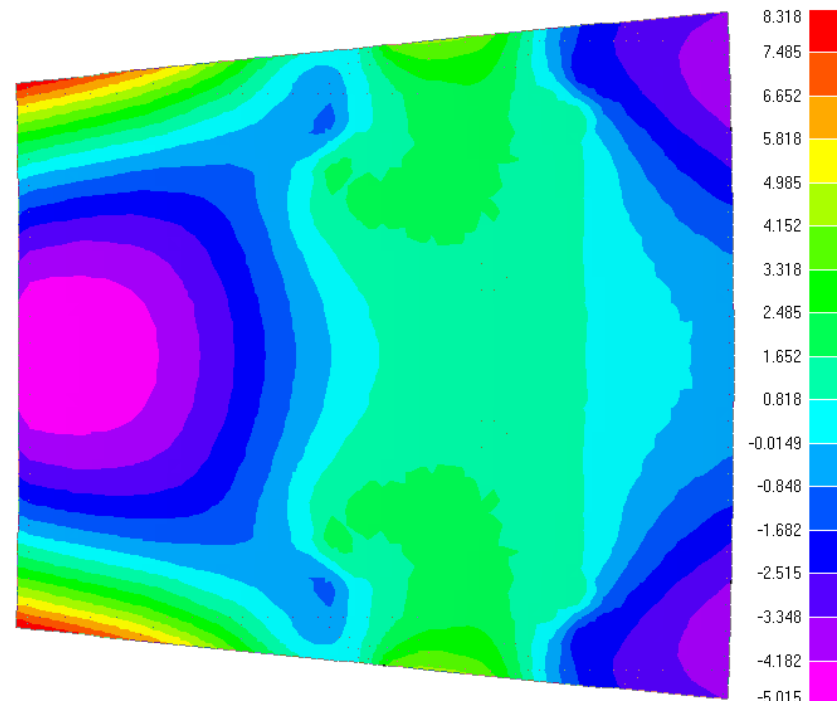
Panel curvature correction system

SFE for panel 4 with $\Delta F = 4$ mm
after adjusting by 3 actuators



RMS = 9.4 μm

Residual SFE for panel 4
after curvature correction



RMS = 2.3 μm



Primary Mirror Error Budget

Panel type / external factor	Panel 1 (central)	Panel 2 (internal)	Panel 3 (middle)	Panel 4 (external)	Total, μm (RMS)
Assembly errors*	0,1	0,3	0,5	0,7	0,3
Inaccuracy of deployment and fixation*	0,0	0,2	0,6	0,9	0,3
Thermal and moisture distortions of framework*	1,5	2,9	3,8	5,8	2,8
Panel curvature correction **	2,4	3,0	2,1	2,3	2,2
1g offload*	0,5	1,0	1,0	1,0	0,8
Panel distortions due to adaptation	0,1	0,2	0,5	0,3	0,2
Adaptation	0,5	0,5	0,5	0,5	0,4
Alignment	1,0	1,0	1,0	1,0	0,9
Non-static image quality	0,2	0,2	0,2	0,2	0,2
Panels	3,0	4,4	4,6	4,6	3,6
Total	13,2	11,2	9,6	10,5	5,3

Note:

* residual RMS got after adaptation via 3 "tip&tilt" actuators per panel and SM

** residual RMS got after curvature correction $\Delta F = 4 \text{ mm}$

More details about panel adaptation in the presentation of A. Baryshev "In-flight Surface Error measurement system"

Conclusions

1. Testing of the full-scale mock-up of the primary mirror is finished:

- ✓ Achieved deployment accuracy - 0.3 mm (PV)
- ✓ Locking systems for operational and stowed configurations have been verified
- ✓ Dynamic performances are acceptable for launch-vehicle

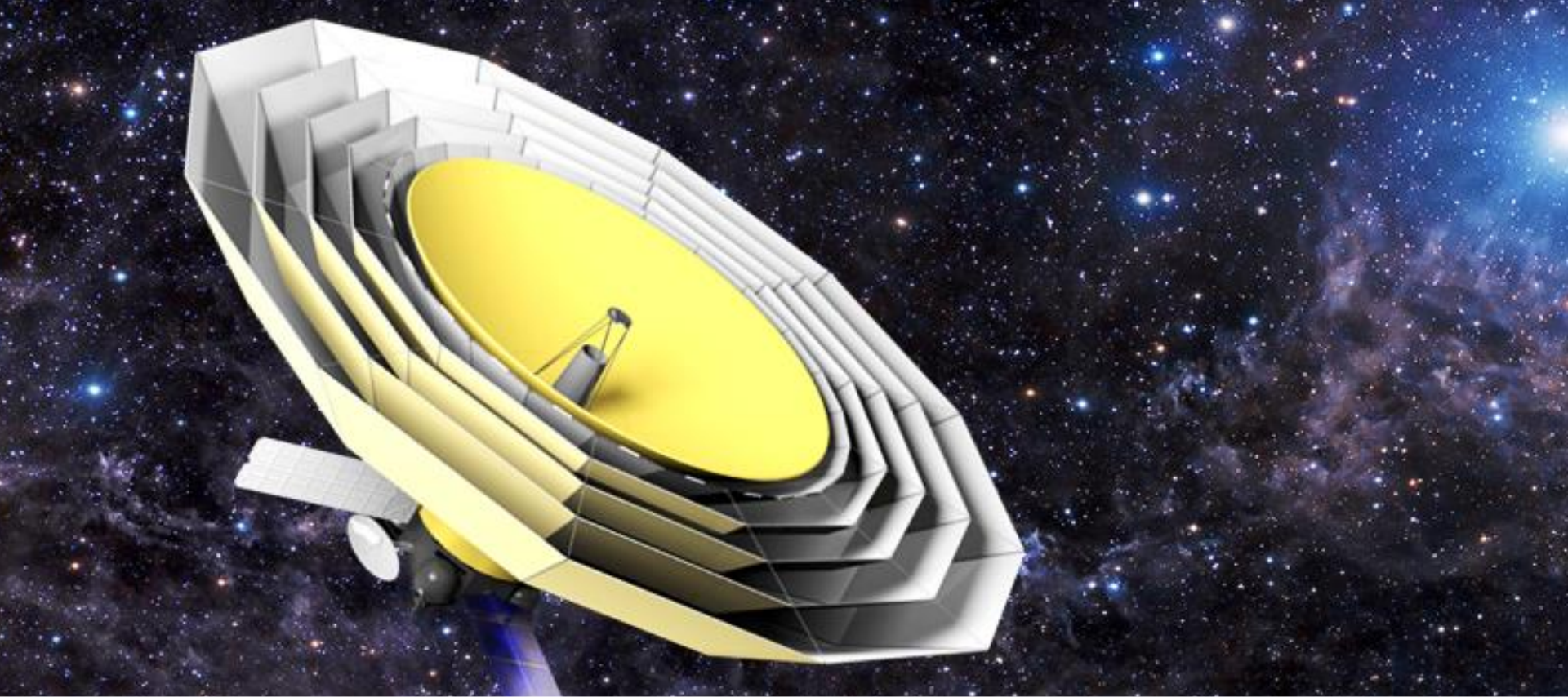
2. Thermal dimensional stability of the primary mirror components:

- ✓ Thermal distortions of the petal framework (cool down to 120K) ≤ 0.4 mm (PV)
- ✓ Thermal distortions of the panel by cooling to 120K not exceeded the 19 μm (PV)

→ More details
in next
presentation

3. Panels position and curvature adjustment

- ✓ Kinematic scheme of the panel adjustment provides compensations of all misalignment factors and meet error budget requirements
- ✓ Algorithm of panels adjustment validated
- ✓ Curvature correction on-board system can handle with the focus length deviation in the range of ± 4 mm



Thank you for your attention