Foreground challenges for measurements of spectral distortions

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Lightening recap of spectral distortions



CMB: Spectral distortions vs Spatial anisotropies



Foreground challenges for measurement of spectral distortions

PROGRESS

Requirements for "measuring" spectral distortions?

Why?

- Sensitivity (~ 0.01 Jy)
- Many many channels (~20-100s) (think spectroscopy)
- Good channel calibration (absolute calibration not essential.)
- Sky coverage

- Signals are small!
- Many many foregrounds (+ ones we have not seen yet)
- Variation in signals are small.
- In principle, single pixel measurement is enough. But, sky coverage is expected to help with mitigating the foregrounds challenge.

Visualizing the signal space



Visualizing the foregrounds space



Here's a "BASIC" model for our data



FTS concepts targeting spectral distortion measurements



Data model and forecasting procedure



Non-linear optimization problem

M. Abitbol, J. Chluba, J. C. Hill and B. R. Johnson et. al. MNRAS (2017) 471 (1): 1126-1140

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10 Sept.'19

Voyage 2050



Voyage 2050 white paper: arXiv:1909.01593

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Observers assumption (current)



Reality in nature





Describing SED resulting from sum of modified black bodies:

$$S_{\nu} = \int \frac{dI}{ds} ds = \int B_{\nu}(\alpha, T) P(\alpha, T) d\alpha dT$$

Building on top of the simple parametrization:

$$S_{\nu} = \sum_{m,n} \partial_{\alpha}^{m} \partial_{T}^{n} B_{\nu}(\alpha_{0}, T_{0}) \int (\alpha - \alpha_{0})^{m} (T - T_{0})^{n} P(\alpha, T) d\alpha dT$$

Moments of the distribution function

$$\begin{split} S_{\nu}(\alpha_{0}, T_{0}, A, p_{\alpha}, p_{T}, p_{\alpha\alpha}, p_{\alpha T}, p_{TT}, \cdots) &\simeq AB_{\nu}(\alpha_{0}, T_{0}) \\ &+ p_{\alpha}\partial_{\alpha}B_{\nu}(\alpha_{0}, T_{0}) + p_{T}\partial_{T}B_{\nu}(\alpha_{0}, T_{0}) \\ &+ p_{\alpha\alpha}\partial_{\alpha}^{2}B(\alpha_{0}, T_{0}) + p_{\alpha T}\partial_{\alpha}\partial_{T}B(\alpha_{0}, T_{0}) + p_{TT}\partial_{T}^{2}B(\alpha_{0}, T_{0}) \end{split}$$

Measuring moments

Spectro-Spatial

$$S_{\nu}(\alpha_{0}, T_{0}, A, p_{\alpha}, p_{T}, p_{\alpha\alpha}, p_{\alpha T}, p_{TT}, \cdots) = \sum_{i} \overrightarrow{B}_{\nu i}(\alpha_{0}, T_{0}) \mathscr{M}_{i} + \epsilon_{i}$$

A deconvolution problem: need to solve both for the kernel as well as the map.

J. Chluba, J. C. Hill & M. H. Abitbol, MNRAS, Vol. 472, Iss. 1, 1195-1213

How many moments to model foregrounds to desired accuracy?



- SED evaluated from sky sims. generated using Python Sky Model (fsky=0.66)
- These moments are generated from spatial averaging.
- One expects similar order of magnitude moments arising from line of sight averaging

Forecasts including all necessary moments (no noise)

IN PRINCIPLE DEMONSTRATION OF REAL WORLD SUB-PERCENT LEVEL MEASUREMENTS OF SPECTRAL DISTORTIONS



This is way beyond currently attempted precision foreground modeling !

- Given current understanding of foregrounds, in principle it might be possible to measure spectral distortions.
- Need to foresee, yet unseen foreground components (eg. Moments for extra-galactic CO, AME ??)
- How to explore spatial information on foregrounds?
- Millimetron could present exciting possibilities for spectral distortion science.